



A phasor is a vector whose length is proportional to the maximum value of the variable it represents, and which rotates counterclockwise at an angular speed equal to the angular frequency associated with the variable. The projection of the phasor onto the vertical axis represents the instantaneous value of the quantity it represents.



NOTES...

- Although we have indicated phasor rotation in Figure 15– 35 by a series of "snapshots," this is too cumbersome; in practice, we show only the phasor at its t = 0 s (reference) position and imply rotation rather than show it explicitly.
- 2. Although we are using maximum values (E_m and I_m) here, phasors are normally drawn in terms of effective values (considered in Section 15.9). For the moment, we will continue to use maximum values. We make the change in Chapter 16.

Time





$$i_{L} = \frac{\Delta V_{\max}}{L} \int \sin \omega t \, dt = -\frac{\Delta V_{\max}}{\omega L} \cos \omega t$$

$$\cos \omega t = -\sin(\omega t - \pi/2)$$

$$i_{L} = \frac{\Delta V_{\max}}{\omega L} \sin \left(\omega t - \frac{\pi}{2}\right)^{2}$$

$$i_{L} = \frac{\Delta V_{\max}}{\omega L} \sin \left(\omega t - \frac{\pi}{2}\right)^{2}$$

$$\Delta v = \Delta V_{\max} \sin \omega t = L \frac{di_{L}}{dt}$$

Comparing Equations 1 and 2, we see that the instantaneous current i_L in the inductor and the instantaneous voltage Δv_L across the inductor are out of phase by $(\pi/2)$ rad = 90°.

the current in an inductor always *lags behind the voltage* across the inductor by 90° (one-quarter cycle in time).





The expression for the rms current in an inductor is similar to Equation 33.9, with I_{max} replaced by I_{rms} and ΔV_{max} replaced by ΔV_{rms} .

It must behave in a manner similar to resistance. Notice that because ωL depends on the applied frequency ω , the inductor reacts differently, in terms of offering resistance to current, for different frequencies. For this reason, we define ωL as the <u>inductive</u> <u>reactance</u>:

تُعَرف المقاومة الفعلية للملف في دوائر التيار المتردد بالمفاعلة الحثية X_L

وتساوى:

$$X_L = \omega L = 2\pi f L$$
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$$X_L = \omega L = 2\pi f L$$

تعتمد على L لأن ق د ك الخلفية تزداد بزيادة L. وكذلك على f لأن ق د ك الخلفية X_L تعتمد أيضاً على $\Delta I/\Delta t$ وتكون كبيرة إذا كان التغير في التيار سريعاً و التردد عالياً.

$$\Delta v_L = -L \frac{di_L}{dt} = -\Delta V_{\max} \sin \omega t = -I_{\max} X_L \sin \omega t$$

Quick Quiz 33.4 Consider the AC circuit in Figure 33.8. The frequency of the AC source is adjusted while its voltage amplitude is held constant. The lightbulb will glow the brightest at (a) high frequencies (b) low frequencies (c) The brightness will be the same at all frequencies.







المكثف في دوائر التيار المتردد Capacitors in an AC Circuit



المكثف في دوائر التيار المتردد Capacitors in an AC Circuit

$$\Delta v_C = \Delta V_{\max} \sin \omega t = I_{\max} X_C \sin \omega t$$

Quick Quiz 33.5 Consider the AC circuit in Figure 33.11. The frequency of the AC source is adjusted while its voltage amplitude is held constant. The lightbulb will glow the brightest at (a) high frequencies (b) low frequencies (c) The brightness will be same at all frequencies.





the applied voltage varies sinusoidally with time. It is convenient to assume that the instantaneous applied voltage is given by

 $\Delta v = \Delta V_{\max} \sin \omega t$

while the current varies as

$$i = I_{\max} \sin(\omega t - \phi)$$

First, we note that because the elements are in series, the current everywhere in the circuit must be the same at any instant. That is, the current at all points in a series AC circuit has the same amplitude and phase. (\cdot, \cdot)

دائرة RLC rcuit توالي RLC series Circuit

$$\Delta v_{R} = I_{\max} R \sin \omega t = \Delta V_{R} \sin \omega t$$

$$\Delta v_{R} = I_{\max} R \sin \omega t = \Delta V_{R} \sin \omega t$$
the voltage across the inductor leads the current by 90°
$$\Delta v_{L} = I_{\max} X_{L} \sin \left(\omega t + \frac{\pi}{2}\right) = \Delta V_{L} \cos \omega t$$
the voltage across the capacitor lags behind the current by
$$90^{\circ}$$

$$\Delta v_{C} = I_{\max} X_{C} \sin \left(\omega t - \frac{\pi}{2}\right) = -\Delta V_{C} \cos \omega t$$

$$\Delta v_{U}$$



دائرة RLC توالي RLC series Circuit



(a) The phasor ΔV_R is in phase with the current phasor I_{max} , ΔV_L leads I_{max} by 90°, and ΔV_C lags I_{max} by 90°. The total voltage ΔV_C meloss on engle Φ with L

The total voltage ΔV_{max} makes an angle ϕ with I_{max} .

(b) Simplified version of the phasor diagram.



$$\Delta V_{\max} = \sqrt{\Delta V_R^2 + (\Delta V_L - \Delta V_C)^2} = \sqrt{(I_{\max} R)^2 + (I_{\max} X_L - I_{\max} X_C)^2}$$

$$\Delta V_{\max} = I_{\max} \sqrt{R^2 + (X_L - X_C)^2}$$
(33.24)

Therefore, we can express the maximum current as

$$I_{\max} = \frac{\Delta V_{\max}}{\sqrt{R^2 + (X_L - X_C)^2}}$$

Maximum current in an RLC circuit

Once again, this has the same mathematical form as Equation 27.8. The denominator of the fraction plays the role of resistance and is called the **impedance** *Z* of the circuit:

$$Z \equiv \sqrt{R^2 + (X_L - X_C)^2}$$
(33.25)



Figure 33.16 An impedance triangle for a series *RLC* circuit gives the relationship $Z = \sqrt{R^2 + (X_L - X_C)^2}.$

دائرة RLC series Circuit توالي RLC series

Impedance Values and Phase Angles for Various Combinations of Circuit Elements^a

Circuit Elements	Impedance Z	Phase Angle ϕ
<i>R</i> ●──₩	R	0°
•C	X_C	-90°
L •000•	X_L	+90°
$\bullet - \bigwedge^R - \stackrel{C}{\bullet} \bullet$	$\sqrt{R^2 + X_C^2}$	Negative, between –90° and 0°
•	$\sqrt{R^2 + X_L^2}$	Positive, between 0° and 90°
	$\sqrt{R^2 + (X_L - X_C)^2}$	Negative if $X_C > X_L$ Positive if $X_C < X_L$

الرنين في دوائر RLC توالي Resonance in a Series RLC Circuit

$$I_{rms} = \frac{\Delta V_{rms}}{Z} = \frac{\Delta V_{rms}}{\sqrt{R^2 + (X_L - X_C)^2}}$$

$$X_L = X_C$$

يحدث ذلك عند تردد
$$f_0$$
يسمى تردد الرنين



The tuning circuit of a radio is an important application of a series resonance circuit. The radio is tuned to a particular station (which transmits a specific radiofrequency signal) by varying a capacitor, which changes the resonance frequency of the tuning circuit. When this resonance frequency matches that of the incoming radio wave, the current in the tuning circuit increases.

الرنين في دوائر RLC توالي RLC Circuit الرنين في دوائر

This curve sharpness is usually described by a dimensionless parameter known as the quality factor, denoted by Q:

 $Q = \frac{\omega_0}{\Delta\omega}$



الرنين في دوائر RLC توالي RLC Circuit الرنين في دوائر

Worksheet:2

1- What is the impedance of a series *RLC circuit at resonance?*(a) larger than *R*(b) less than *R*(c) equal to *R*(d) impossible to determine

Example 33.3 A Purely Capacitive AC Circuit

An 8.00- μ F capacitor is connected to the terminals of a 60.0-Hz AC source whose rms voltage is 150 V. Find the capacitive reactance and the rms current in the circuit.

Solution Using Equation 33.18 and the fact that $\omega = 2\pi f = 377 \text{ s}^{-1}$ gives

$$X_C = \frac{1}{\omega C} = \frac{1}{(377 \,\mathrm{s}^{-1})(8.00 \times 10^{-6} \,\mathrm{F})} = 332 \,\Omega$$

Hence, from a modified Equation 33.19, the rms current is

$$I_{\rm rms} = \frac{\Delta V_{\rm rms}}{X_C} = \frac{150 \,\rm V}{332 \,\Omega} = 0.452 \,\rm A$$

What If? What if the frequency is doubled? What happens to the rms current in the circuit?

Answer If the frequency increases, the capacitive reactance decreases—just the opposite as in the case of an inductor. The decrease in capacitive reactance results in an increase in the current.

Let us calculate the new capacitive reactance:

$$X_C = \frac{1}{\omega C} = \frac{1}{2(377 \text{ s}^{-1})(8.00 \times 10^{-6} \text{ F})} = 166 \Omega$$

The new current is

$$I_{\rm rms} = \frac{150 \,\rm V}{166 \,\Omega} = 0.904 \,\rm A$$

Example 33.5 Analyzing a Series RLC Circuit

A series *RLC* AC circuit has $R = 425 \Omega$, L = 1.25 H, $C = 3.50 \mu$ F, $\omega = 377 \text{ s}^{-1}$, and $\Delta V_{\text{max}} = 150$ V.

(A) Determine the inductive reactance, the capacitive reactance, and the impedance of the circuit.

Solution The reactances are $X_L = \omega L = 471 \Omega$ and $X_C = 1/\omega C = 758 \Omega$.

The impedance is

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

= $\sqrt{(425 \ \Omega)^2 + (471 \ \Omega - 758 \ \Omega)^2} = 513 \ \Omega$

H, ve nd

(B) Find the maximum current in the circuit.

Solution

$$I_{\rm max} = \frac{\Delta V_{\rm max}}{Z} = \frac{150 \,\mathrm{V}}{513 \,\Omega} = 0.292 \,\mathrm{A}$$

(C) Find the phase angle between the current and voltage.

Solution

$$\phi = \tan^{-1} \left(\frac{X_L - X_C}{R} \right) = \tan^{-1} \left(\frac{471 \ \Omega - 758 \ \Omega}{425 \ \Omega} \right)$$
$$= -34.0^{\circ}$$

Because the capacitive reactance is larger than the inductive reactance, the circuit is more capacitive than inductive. In this case, the phase angle ϕ is negative and the current leads the applied voltage.